

## ECE 275A Homework # 2 Solutions

1. ECE 174 Midterm solutions are in a separate file located on the class website.
2. Let  $\mathcal{V}$  and  $\mathcal{W}$  be independent (disjoint) subspaces of a vector space  $\mathcal{X}$ , such that  $\mathcal{X} = \mathcal{V} + \mathcal{W}$ .<sup>1</sup> Consider any two vectors  $x = x_1 + x_2$  and  $y = y_1 + y_2$  in  $\mathcal{X}$ , where  $x_1, y_1 \in \mathcal{V}$  and  $x_2, y_2 \in \mathcal{W}$  give the unique decomposition of  $x$  and  $y$  along the companion subspaces  $\mathcal{V}$  and  $\mathcal{W}$  respectively. Let  $P = P_{\mathcal{V}|\mathcal{W}}$  denote the projection operator which projects  $\mathcal{X}$  onto  $\mathcal{V}$  along  $\mathcal{W}$ . Then  $Px = x_1$  and  $Py = y_1$ . For any two scalars  $\alpha$  and  $\beta$  we have

$$\alpha x + \beta y = \alpha(x_1 + x_2) + \beta(y_1 + y_2) = (\alpha x_1 + \beta y_1) + (\alpha x_2 + \beta y_2) \in \mathcal{X},$$

with  $(\alpha x_1 + \beta y_1) \in \mathcal{V}$  and  $(\alpha x_2 + \beta y_2) \in \mathcal{W}$  since  $\mathcal{V}$  and  $\mathcal{W}$  are vector subspaces. Therefore

$$P(\alpha x + \beta y) = \alpha x_1 + \beta y_1 = \alpha Px + \beta Py,$$

showing that a (possibly non-orthogonal) projection operator is linear.

3. Recall the the columns of  $[V \ W]$  are a basis for  $\mathcal{X}$  iff they form a spanning set of vectors for  $\mathcal{X}$  which are also linearly independent. Also recall that a linear operator  $P$  is a projection operator iff it is idempotent,  $P = P^2$ .
  - (a) The complementary subspace condition  $\mathcal{X} = \mathcal{V} \oplus \mathcal{W}$  and the fact that the columns of  $V$  and the columns of  $W$  each respectively forms a basis for  $\mathcal{V}$  and  $\mathcal{W}$  implies that for each  $x \in \mathcal{X}$  there exists a  $v = V\alpha \in \mathcal{V}$  and a  $w = W\beta \in \mathcal{W}$  such that

$$x = v + w = V\alpha + W\beta = [V \ W] \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

showing that the columns of  $[V \ W]$  span  $\mathcal{X}$ .

The complementary subspace condition  $\mathcal{X} = \mathcal{V} \oplus \mathcal{W}$  implies that  $\mathcal{V}$  and  $\mathcal{W}$  are disjoint, which is true iff  $\mathcal{V} \cap \mathcal{W} = \{0\}$ . Now suppose that the columns of  $V$  and  $W$  *taken together* are *not* linearly independent. Then there exists  $\alpha \neq 0$  and  $\beta \neq 0$  such that  $0 = V\alpha + W\beta$ . (Recall that the columns of  $V$  are a linearly independent set, as are the columns of  $W$ .) This yields  $V\alpha = -W\beta \neq 0$ . But  $V\alpha \in \mathcal{V}$  and  $-W\beta \in \mathcal{W}$ , implying that

$$0 \neq V\alpha \in \mathcal{V} \cap \mathcal{W}$$

which contradicts the assumption that  $\mathcal{V}$  and  $\mathcal{W}$  are disjoint,  $\mathcal{V} \cap \mathcal{W} = \{0\}$ . Therefore the assumption that the columns of  $V$  and  $W$  taken together are not linearly independent must be incorrect.

---

<sup>1</sup>I.e., let  $\mathcal{V}$  and  $\mathcal{W}$  be *companion* subspaces of  $\mathcal{X}$ .

(b) Note that to show that a linear operator is a projection operator onto  $\mathcal{V}$  we need to show both that it is *idempotent* (i.e., that it is indeed a *projector*) and that *its range is  $\mathcal{V}$*  (i.e., that it is a projector *onto*  $\mathcal{V}$ ). Let  $n$  be the dimension of  $\mathcal{X}$ . With the columns  $M = [V \ W]$  linearly independent,  $M$  is an  $n \times n$  invertible matrix.

Consider the matrix

$$P = M \begin{pmatrix} I & 0 \\ 0 & 0 \end{pmatrix} M^{-1} = [V \ 0] M^{-1}.$$

It is easily shown that  $P^2 = P$ , so that  $P$  is a projection operator.

Because  $P = [V \ 0] M^{-1}$ , we have that  $\mathcal{R}(P) = \mathcal{R}(V) = \mathcal{V}$ . Thus  $P$  is a projector from  $\mathcal{X}$  onto the subspace  $\mathcal{V} \subset \mathcal{X}$ .

We now need to show that  $P$  projects “along”  $\mathcal{W}$ , which is equivalent to the requirement that  $\mathcal{N}(P) = \mathcal{R}(W)$ , i.e. that  $0 = Px$  for all  $x \in \mathcal{W}$ . This is readily shown:

$$x \in \mathcal{R}(W) \iff x = W\beta = [V \ W] \begin{pmatrix} 0 \\ \beta \end{pmatrix} = M \begin{pmatrix} 0 \\ \beta \end{pmatrix} \implies Px = [V \ 0] M^{-1} M \begin{pmatrix} 0 \\ \beta \end{pmatrix} = 0.$$

4. Proof of Fact 1:

$$\begin{aligned} \langle x_1, \alpha x_2 \rangle &= \alpha \langle x_1, x_2 \rangle && \text{(assuming linearity in the second argument)} \\ &= \overline{\overline{\alpha} \langle x_2, x_1 \rangle} \\ &= \langle x_2, \overline{\alpha} x_1 \rangle \\ &= \langle \overline{\alpha} x_1, x_2 \rangle . \end{aligned}$$

Proof of Fact 2:

$$\begin{aligned} \langle x_1 + x_2, x \rangle &= \overline{\langle x, x_1 + x_2 \rangle} \\ &= \overline{\langle x, x_1 \rangle + \langle x, x_2 \rangle} && \text{(assuming linearity in the second argument)} \\ &= \langle x_1, x \rangle + \langle x_2, x \rangle . \end{aligned}$$

Proof of Fact 3:

$$\begin{aligned} \langle \alpha_1 x_1 + \alpha_2 x_2, x \rangle &= \langle \alpha_1 x_1, x \rangle + \langle \alpha_2 x_2, x \rangle && \text{(from Fact 2)} \\ &= \overline{\overline{\alpha_1} \langle x_1, x \rangle + \overline{\alpha_2} \langle x_2, x \rangle} . && \text{(from Fact 1)} \end{aligned}$$

Proof of Fact 4: For all vectors  $x \in \mathcal{X}$ , for all vectors  $y_1, y_2 \in \mathcal{Y}$ , and for all scalars  $\alpha_1, \alpha_2 \in \mathbb{C}$ ,

$$\begin{aligned} \langle A^* (\alpha_1 y_1 + \alpha_2 y_2), x \rangle &= \langle \alpha_1 y_1 + \alpha_2 y_2, Ax \rangle \\ &= \overline{\overline{\alpha_1} \langle y_1, Ax \rangle + \overline{\alpha_2} \langle y_2, Ax \rangle} && \text{(from Fact 3)} \\ &= \overline{\overline{\alpha_1} \langle A^* y_1, x \rangle + \overline{\alpha_2} \langle A^* y_2, x \rangle} \\ &= \langle \alpha_1 A^* y_1 + \alpha_2 A^* y_2, x \rangle , && \text{(from Fact 3)} \end{aligned}$$

and therefore  $A^*(\alpha_1 y_1 + \alpha_2 y_2) = \alpha_1 A^* y_1 + \alpha_2 A^* y_2$ . (Why does this last step follow?<sup>2</sup>)

Proof of Fact 5: For all  $x$  and  $y$ ,

$$\begin{aligned} \langle (\alpha A)^* y, x \rangle &= \langle y, \alpha A x \rangle \\ &= \alpha \langle y, A x \rangle \\ &= \alpha \langle A^* y, x \rangle \\ &= \langle \bar{\alpha} A^* y, x \rangle, \quad (\text{from Fact 1}) \end{aligned}$$

and therefore  $(\alpha A)^* = \bar{\alpha} A^*$ . (Why?)

Proof of Fact 6: For all  $x$  and  $y$ ,

$$\begin{aligned} \langle (A + B)^* y, x \rangle &= \langle y, (A + B)x \rangle \\ &= \langle y, Ax \rangle + \langle y, Bx \rangle \\ &= \langle A^* y, x \rangle + \langle B^* y, x \rangle \\ &= \langle A^* y + B^* y, x \rangle \quad (\text{from Fact 2}) \\ &= \langle (A^* + B^*) y, x \rangle \quad (\text{from definition of addition of operators}) \end{aligned}$$

and therefore  $(A + B)^* = A^* + B^*$ . (Why?)

Proof of Fact 7:

$$\begin{aligned} (\alpha A + \beta B)^* &= (\alpha A)^* + (\beta B)^* \quad (\text{from Fact 5}) \\ &= \bar{\alpha} A^* + \bar{\beta} B^*. \quad (\text{from Fact 4}) \end{aligned}$$

Proof of Fact 8: For all  $x$  and  $y$ ,

$$\langle A^* y, x \rangle = \langle y, Ax \rangle \Leftrightarrow \overline{\langle x, A^* y \rangle} = \overline{\langle Ax, y \rangle} \Leftrightarrow \langle x, A^* y \rangle = \langle Ax, y \rangle .$$

Proof of Fact 9: For all  $x$  and  $z$ ,

$$\langle (CA)^* z, x \rangle = \langle z, CAx \rangle = \langle C^* z, Ax \rangle = \langle A^* C^* z, x \rangle ,$$

and therefore  $(CA)^* = A^* C^*$ . (Why?)

5. Moon 3.8.10. Let a linear mapping,  $\mathcal{A} : \mathbb{C}^m \rightarrow \mathbb{C}^{p \times q}$ , between the space of complex  $m$ -vectors and complex  $p \times q$ -matrices be given by,

$$\mathcal{A}c = \sum_{i=1}^m c_i X_i .$$

---

<sup>2</sup>On an exam, I can ask you to fill in *every* step of the proof, *including* the ones not explicitly given here.

The inner product on  $\mathbb{C}^m$  is taken to be the standard inner product,  $\langle x, y \rangle = x^H y$ , while the inner product on  $\mathbb{C}^{p \times q}$  is taken to be the Frobenius inner product,

$$\langle X, Y \rangle = \text{tr } X^H Y .$$

Assume that  $X_i$  are linearly independent so that the mapping,  $\mathcal{A}$ , is one-to-one. We wish to solve the (possibly inconsistent) inverse problem,

$$Y = \mathcal{A} c ,$$

The normal equations are,

$$\mathcal{A}^* \mathcal{A} c = \mathcal{A}^* Y , \tag{1}$$

which, since  $\mathcal{A}$  is one-to-one, yields the least squares solution,

$$\hat{c} = \mathcal{A}^+ Y = (\mathcal{A}^* \mathcal{A})^{-1} \mathcal{A}^* Y . \tag{2}$$

To obtain the normal equations (1) and the least squares solution (2) it is evident that we need to compute the so-called *Grammian operator*  $\mathcal{A}^* \mathcal{A}$  and the *cross-correlation vector*  $\mathcal{A}^* Y$ . (These terms are defined in Section 3.1 of Moon.) The adjoint operator is determined from,

$$\begin{aligned} \langle Y, \mathcal{A} c \rangle &= \left\langle Y, \sum_{i=1}^m c_i X_i \right\rangle = \sum_{i=1}^m c_i \langle Y, X_i \rangle \\ &= \sum_{i=1}^m \overline{\langle X_i, Y \rangle} c_i = \langle \mathcal{A}^*(Y), c \rangle . \end{aligned}$$

This yields,

$$\mathcal{A}^*(Y) = \begin{pmatrix} \langle X_1, Y \rangle \\ \vdots \\ \langle X_m, Y \rangle \end{pmatrix} = \begin{pmatrix} \text{tr } X_1^H Y \\ \vdots \\ \text{tr } X_m^H Y \end{pmatrix} \in \mathbb{C}^m , \tag{3}$$

which is precisely the cross-correlation vector given as Equation (3.5) of Moon. (Because we define linearity in the *second* argument, our inner product arguments are reversed compared to Moon, who defines linearity to be in the first argument.) Taking  $Y = \mathcal{A} c$  in the above enables us to determine  $\mathcal{A}^* \mathcal{A}$ . In particular, note that the  $i^{\text{th}}$  component of the  $m$ -vector  $\mathcal{A}^* \mathcal{A} c$  is given by,

$$\begin{aligned} (\mathcal{A}^* \mathcal{A} c)_i &= \langle X_i, \mathcal{A} c \rangle = \left\langle X_i, \sum_{j=1}^m c_j X_j \right\rangle \\ &= \sum_{j=1}^m c_j \langle X_i, X_j \rangle = (\langle X_i, X_1 \rangle, \dots, \langle X_i, X_m \rangle) c . \end{aligned}$$

This shows that the full Grammian matrix is given by (cf. Equation (3.7) of Moon),

$$\mathcal{A}^* \mathcal{A} = \begin{pmatrix} \langle X_1, X_1 \rangle & \cdots & \langle X_1, X_m \rangle \\ \vdots & \ddots & \vdots \\ \langle X_m, X_1 \rangle & \cdots & \langle X_m, X_m \rangle \end{pmatrix} = \begin{pmatrix} \text{tr } X_1^H X_1 & \cdots & \text{tr } X_1^H X_m \\ \vdots & \ddots & \vdots \\ \text{tr } X_m^H X_1 & \cdots & \text{tr } X_m^H X_m \end{pmatrix}. \quad (4)$$

Equations (1)–(4) taken together yield the least-squares solution.

6. From Equation (1.2) of Moon we have (with  $a_0 = 1$ ),

$$y[t] = -\bar{a}_1 y[t-1] - \cdots - \bar{a}_p y[t-p] + \bar{b}_0 f[t] + \cdots + \bar{b}_q f[t-q] = x^H r[t], \quad (5)$$

where,

$$x = (a_1, \cdots, a_p, \cdots, b_0, \cdots, b_q)^T \in \mathbb{C}^{p+q+1},$$

and

$$r[t] = (-y[t-1], \cdots, -y[t-p], f[t], \cdots, f[t-q])^T \in \mathbb{C}^{p+q+1}.$$

Note that we can rewrite (5) as

$$\bar{y}[t] = r^H[t] x. \quad (6)$$

Now suppose we have collected data sufficient to fill in the values of  $y[t]$  and  $r[t]$  for  $t = 1, \cdots, m$ . Then (6) enables us to fill in the  $m$  rows of the following vector-matrix equation,

$$\begin{pmatrix} \bar{y}[1] \\ \vdots \\ \bar{y}[m] \end{pmatrix} = \begin{pmatrix} r^H[1] \\ \vdots \\ r^H[m] \end{pmatrix} x,$$

which we can write as,

$$\eta = Ax, \quad (7)$$

where,

$$\eta = \begin{pmatrix} \bar{y}[1] \\ \vdots \\ \bar{y}[m] \end{pmatrix} \in \mathbb{C}^m \quad \text{and} \quad A = \begin{pmatrix} r^H[1] \\ \vdots \\ r^H[m] \end{pmatrix} \in \mathbb{C}^{m \times (p+q+1)}. \quad (8)$$

The system (7)–(8) can be solved in the least-squares sense to yield estimates of the unknown parameter vector,  $x$ . Note that this is a purely *data-driven* approach and (other than the putative validity of the ARMA model assumption) no statistical information about the data (such as knowledge of correlations) is assumed. The data  $y[0], \cdots, y[p-1], \cdots, f[0], \cdots, f[-q]$  are known as the *initial conditions*. If they are not available, their values are often (suboptimally) set to zero. This is usually a reasonable approximation when  $m \gg (p+q+1)$ .

7. Proof of Moon Equation (4.34):

$$\begin{aligned}
(A + XRY)^{-1}XR &= A^{-1}X(R^{-1} + YA^{-1}X)^{-1}; & (\text{Moon Eq. (4.34)}) \\
XR &= (A + XRY)A^{-1}X(R^{-1} + YA^{-1}X)^{-1}; \\
XR(R^{-1} + YA^{-1}X) &= (A + XRY)A^{-1}X; \\
X + XRYA^{-1}X &= X + XRYA^{-1}X; \\
X &= X.
\end{aligned}$$

Proof of Moon Equation (4.33):

$$\begin{aligned}
(A + XRY)^{-1} &= A^{-1} - A^{-1}X(R^{-1} + YA^{-1}X)^{-1}YA^{-1} & (\text{Moon Eq. (4.33)}) \\
&= A^{-1} - (A + XRY)^{-1}XRYA^{-1}; & (\text{Using Moon Eq. (4.34)}) \\
I &= (A + XRY)A^{-1} - XRYA^{-1} \\
&= I + XRYA^{-1} - XRYA^{-1} = I.
\end{aligned}$$

To show the validity of Moon Equation (4.32), take  $R = I$ ,  $X = x$ , and  $Y = y^H$  in Moon Equation (4.33).

8. Kay 8.10. Write the vector  $x$  as,

$$x = x + \hat{s} - \hat{s} = \hat{s} + (x - \hat{s}) = \hat{s} + e,$$

where  $\hat{s}$  is the orthogonal projection of  $x$  onto the subspace. Note that  $e = x - \hat{s}$  is orthogonal to  $\hat{s}$ ,  $\langle e, \hat{s} \rangle = \langle \hat{s}, e \rangle = 0$ , as a consequence of the Orthogonality Principle. Exploiting this fact results in,

$$\|x\|^2 = \|\hat{s} + e\|^2 = \langle \hat{s} + e, \hat{s} + e \rangle = \langle \hat{s}, \hat{s} \rangle + \langle e, e \rangle = \|\hat{s}\|^2 + \|e\|^2.$$

9. Let  $\mathbb{C}^n$  be the space of  $n$ -dimensional vectors over the field of complex numbers with the standard inner product,

$$\langle x_1, x_2 \rangle = x_1^H x_2,$$

and corresponding induced 2-norm,

$$\|x\|_2 = \sqrt{x^H x}.$$

Let  $\mathbf{RV}^m$  be the Hilbert space of zero mean, finite second-order moment  $m$ -dimensional random vectors over the field of complex numbers with inner product,

$$\langle y_1, y_2 \rangle = \mathbb{E} \{ y_1^H(\omega) y_2(\omega) \},$$

with corresponding induced norm,

$$\|y\|^2 = \mathbb{E} \{ \|y(\omega)\|_2^2 \},$$

where  $\|y(\omega)\|_2$  here denotes the standard 2-norm on  $\mathbb{C}^m$ . (As is standard, random vectors are identified as equivalent if they are identical almost surely.) Let

$$\mathcal{A} : \mathbb{C}^n \rightarrow \text{RV}^m$$

be defined by

$$\mathcal{A}(x) = A(\omega)x,$$

where  $A$  is a random  $m \times n$  matrix whose columns belong to, and are linearly independent in, the space  $\text{RV}^m$ ,

$$A(\omega) = [a_1(\omega), \dots, a_n(\omega)], \quad a_i \in \text{RV}^m, \quad i = 1, \dots, n.$$

Because the  $n$  columns of  $A(\omega)$  belong to  $\text{RV}^m$ , they each have zero mean. Furthermore, since they are assumed to be linearly independent in the space  $\text{RV}^m$ , they each must be nonzero with probability one.

Given an arbitrary random vector,  $y \in \text{RV}^m$ , we wish to find the minimum mean-square error approximation to  $y$  in the range of  $\mathcal{A}$ . This is equivalent to determining a vector  $\hat{x}$  such that,

$$\hat{x} \in \text{argmin } \text{E} \{ \|y(\omega) - \mathcal{A}(x)\|_2^2 \} = \text{argmin } \text{E} \{ \|y(\omega) - A(\omega)x\|_2^2 \}.$$

Equivalently, we desire to solve  $y \approx \mathcal{A}(x)$  in the least-squares sense. The standard application of the projection theorem in the codomain of  $\mathcal{A}$  yields the Normal Equations,

$$\mathcal{A}^* \mathcal{A} \hat{x} = \mathcal{A}^* y,$$

which we write as

$$R_{AA} \hat{x} = R_{Ay},$$

where,

$$R_{AA} = \mathcal{A}^* \mathcal{A} \quad \text{and} \quad R_{Ay} = \mathcal{A}^* y.$$

With the assumption that the columns of  $A(\omega)$  are linearly independent as random vectors in  $\text{RV}^m$ , we will see below that  $R_{AA} = \mathcal{A}^* \mathcal{A}$  is invertible (one-to-one) and hence  $\mathcal{A}$  is one-to-one. *Therefore the least squares solution is unique and is the unique solution to the Normal Equations.*

To determine the adjoint operator,  $\mathcal{A}^*$ , note that,

$$\langle y, \mathcal{A}(x)x \rangle = \text{E} \{ y^H A x \} = (\text{E} \{ A^H y \})^H x = \langle \text{E} \{ A^H y \}, x \rangle, \quad (9)$$

and therefore,

$$\mathcal{A}^* y = R_{Ay} = \text{E} \{ A^H y \}.$$

Now note that,

$$\mathcal{A}^*(\mathcal{A}x) = \text{E} \{ A^H (Ax) \} = \text{E} \{ A^H A \} x$$

Since this is true for all  $x$ , the operator  $R_{AA} = \mathcal{A}^* \mathcal{A}$  is seen to be,

$$\mathcal{A}^* \mathcal{A} = R_{AA} = \mathbf{E} \{A^H A\} = \text{diag} (\|a_1\|^2, \dots, \|a_m\|^2),$$

which is invertible since  $\|a_i\| \neq 0$ ,  $i = 1, \dots, m$ .<sup>3</sup> Thus we have determined that the minimum mean-square estimate of  $y$  is given by  $\hat{y} = \mathcal{A} \hat{x}$  where  $\hat{x}$  is the unique least-squares (pseudoinverse) solution

$$\hat{x} = R_{AA}^{-1} R_{Ay} = (\mathbf{E} \{A^H A\})^{-1} \mathbf{E} \{A^H y\}.$$

Note that we have shown that,

$$\mathcal{A}^+ y = (\mathbf{E} \{A^H A\})^{-1} \mathbf{E} \{A^H y\},$$

and

$$\hat{y} = P_{\mathcal{R}(A)} y = \mathcal{A} \hat{x} = \mathcal{A} \mathcal{A}^+ y = A \left( (\mathbf{E} \{A^H A\})^{-1} \mathbf{E} \{A^H y\} \right).$$

Since this is true for all  $y \in \mathbf{RV}^m$ , we have shown that the orthogonal projector onto the range of  $\mathcal{A}$  is given by

$$P_{\mathcal{R}(A)}(\cdot) = A \left( (\mathbf{E} \{A^H A\})^{-1} \mathbf{E} \{A^H(\cdot)\} \right).$$

10. Fredholm's Alternative. Condition (a) says that  $b$  is in the range of  $A$ . Condition (b) says that  $b$  is not in the range of  $A$ . Obviously these conditions are mutually exclusive and one and only one of them is true.

---

<sup>3</sup>Recall that  $a_i \neq 0$  by assumption that the columns of  $A$  are linearly independent in  $\mathbf{RV}^m$ .